

A generalization of the volume conjecture

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Generalization to three-manifolds

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$$2\pi \lim_{N \rightarrow \infty} \frac{\log J_N (K; \exp(2\pi\sqrt{-1}/N))}{N} \\ = \text{Vol}(S^3 \setminus K) + \sqrt{-1} \text{CS}(S^3 \setminus K).$$

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to be continued...

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The limit
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- $a = u + 2\pi\sqrt{-1}$.

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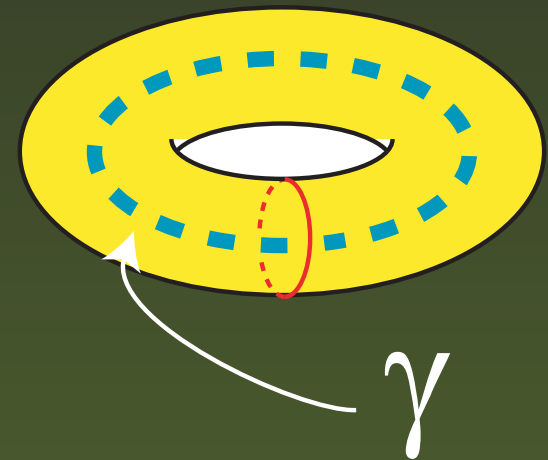
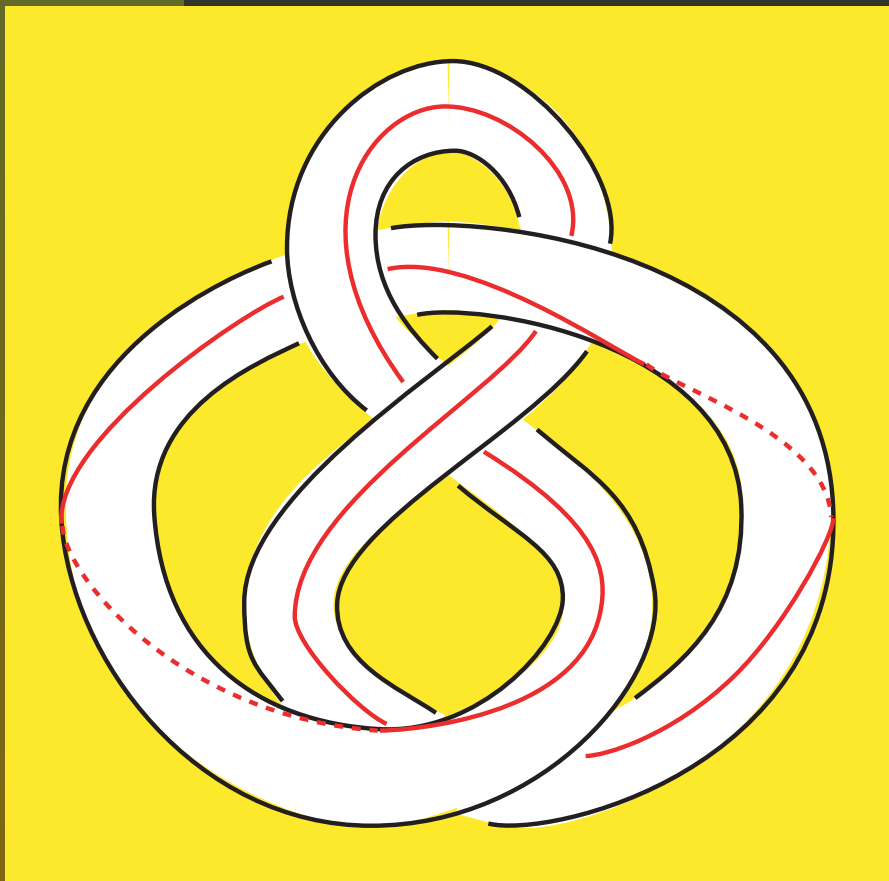
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- γ : core of the attached solid torus with length length.
- p/q is determined by $pu + qv = 2\pi\sqrt{-1}$.
- Chern–Simons invariant can also be obtained (later).

Dehn surgery



Identifying two red circles, we get the $2/1$ -surgery.

Analytic version of MMR conjecture

Theorem. (analytic version of the Melvin–Morton–Rozansky conjecture) (S. Garoufalidis and T. Le)

For any knot K ,

$$\lim_{N \rightarrow \infty} J_N(K; \exp(a/N)) = \frac{1}{\Delta(K; \exp a)}$$

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- We do *not* divide by N in the limit.

Result on torus knots

Theorem. (HM)

$$\lim_{N \rightarrow \infty} \frac{\log J_N (T(\alpha, \beta); \exp(a/N))}{N} = \pi \sqrt{-1} + \frac{\pi^2}{\alpha \beta a} - \frac{\alpha \beta a}{4}.$$

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- $T(\alpha, \beta)$: torus knot.
- $|a| > \frac{2\pi}{\alpha\beta}$, $\operatorname{Re}(a) < 0$, and $\operatorname{Im}(a) > 0$.

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$\left\{ \begin{array}{l} \text{quantity that gives Vol} \quad \text{for } \textcircled{8}, \\ 0 \quad \text{if } |a| \text{ is small,} \\ \text{strange quantity} \quad \text{for torus knots.} \end{array} \right.$

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- For small $|a|$, \heartsuit is 0!
 - For torus knots, \heartsuit is also 0!!
- \Rightarrow Can we relate \heartsuit to a kind of volume?

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$$\rho: \begin{cases} \text{meridian} & \mapsto \begin{pmatrix} \exp(u/2) & * \\ 0 & \exp(-u/2) \end{pmatrix}, \\ \text{longitude} & \mapsto \begin{pmatrix} \exp(v/2) & * \\ 0 & \exp(-v/2) \end{pmatrix}. \end{cases}$$

Volume function

- $V(K; u)$ satisfies Schläfli's formula:

$$dV(K; u)$$


$$= -\frac{1}{2} \{ \operatorname{Re}(u) d \operatorname{Im}(v) - \operatorname{Re}(v) d \operatorname{Im}(u) \} .$$

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⇒ The conjecture is true for

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- any knot with small $|a|$,
- torus knots.

Chern–Simons invariant?

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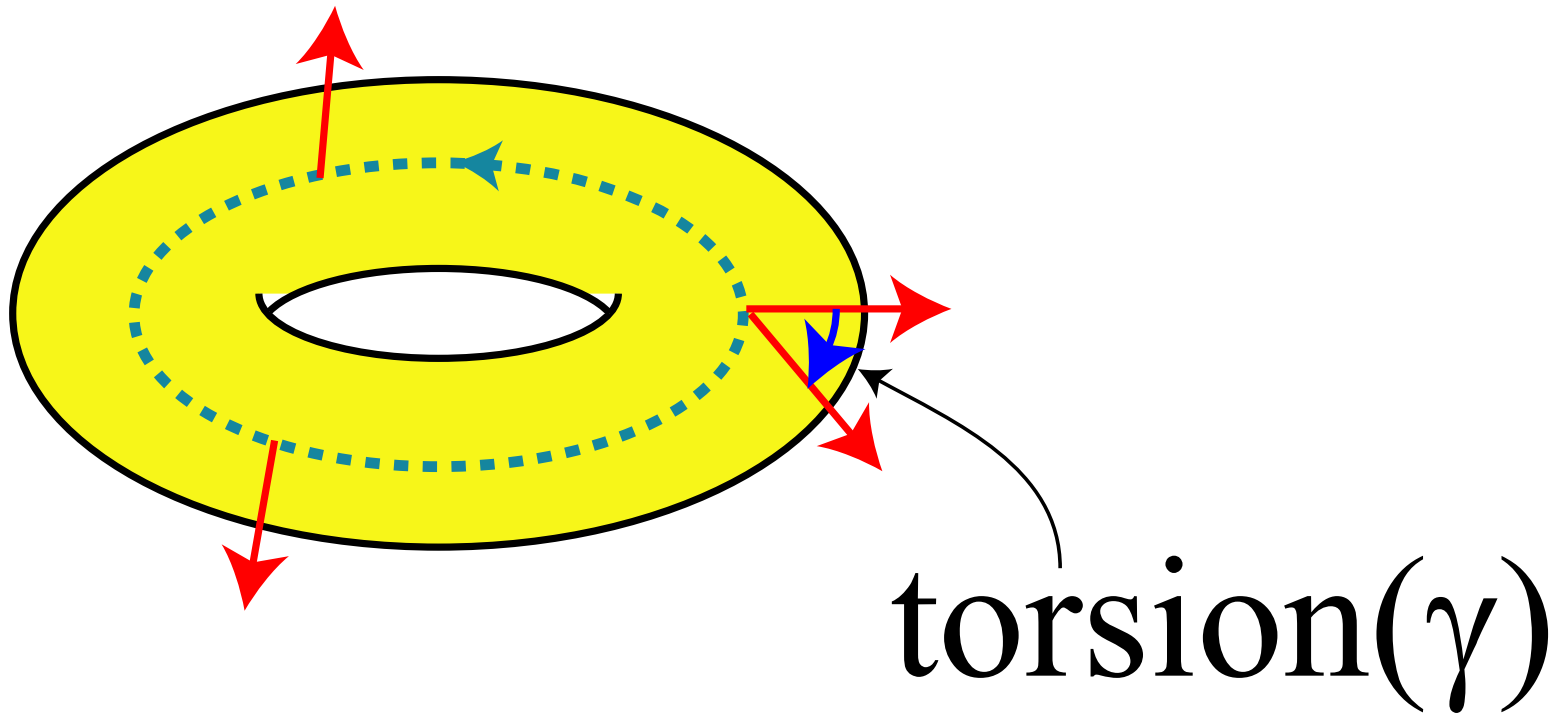
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- \mathfrak{S}_u is the 3-manifold obtained by Dehn surgery along \mathfrak{S} corresponding to u .

Torsion



$\text{torsion}(\gamma)$ measures how much the normal vector is twisted when it travels along γ in \mathcal{S}_u .

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